

Internet2 Network Control Plane Strategy

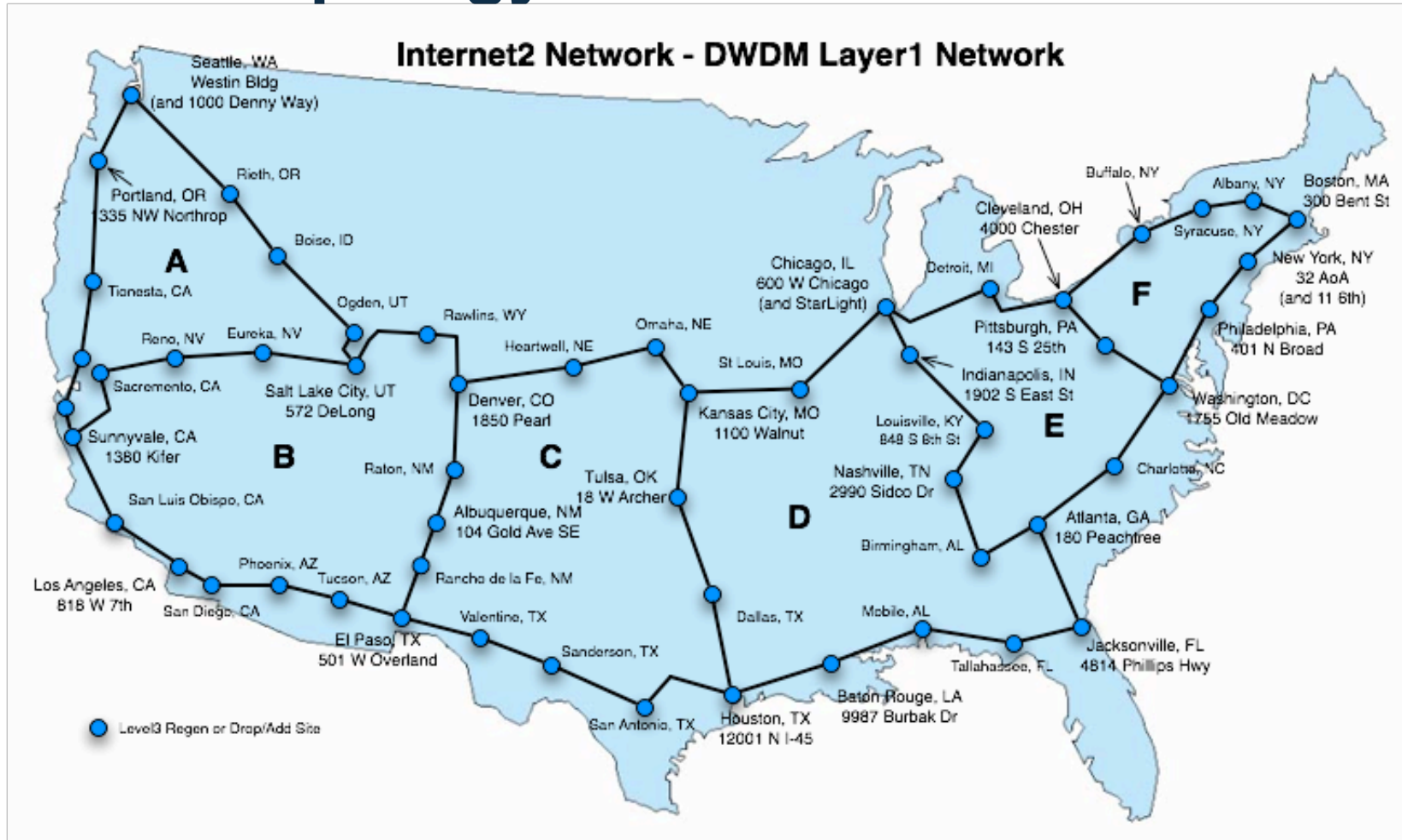
Rick Summerhill
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Internet2

GLIF Meeting
12 September 2006
Tokyo, Japan

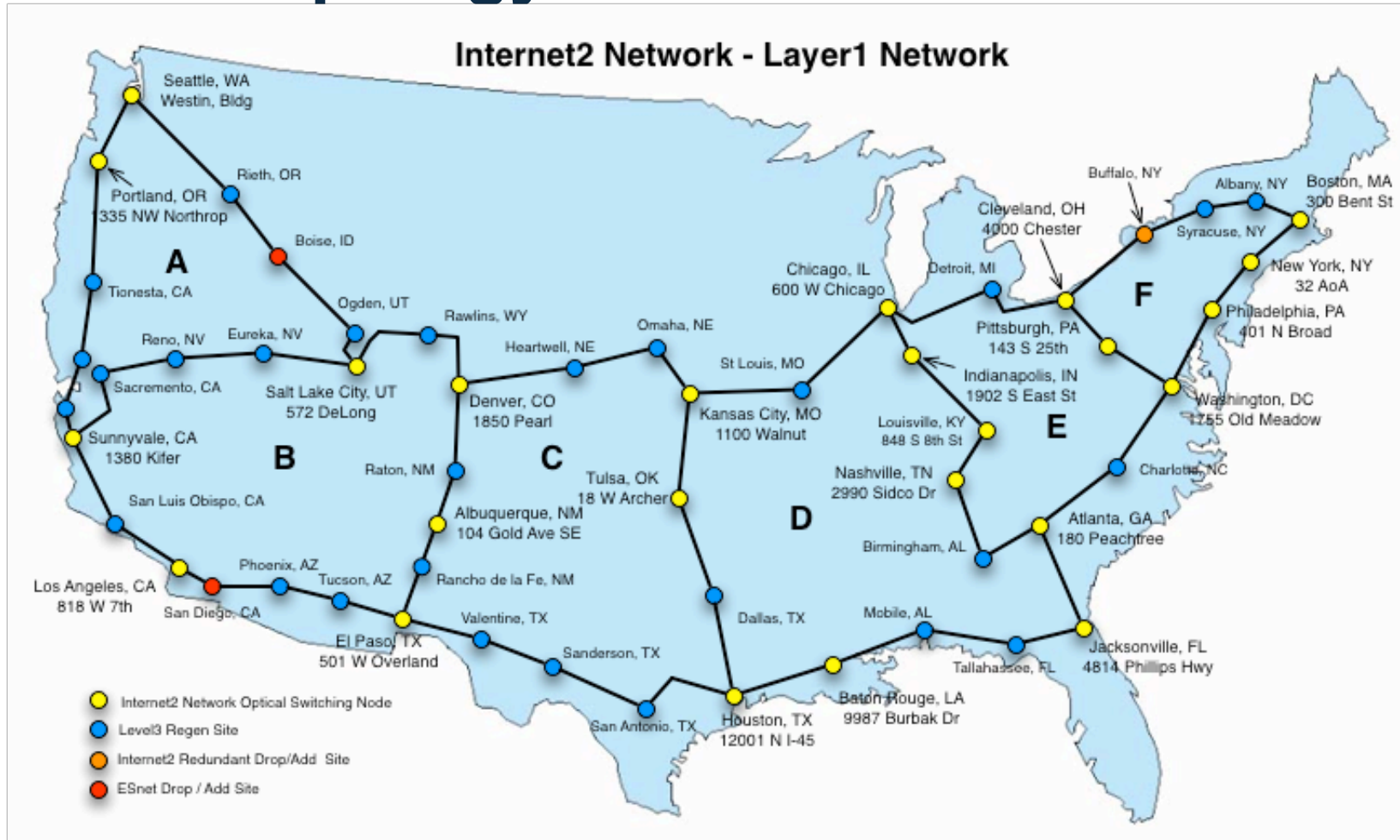
Agenda

- Basic Ideas
- Topology
- Optical nodes
- Control Plane

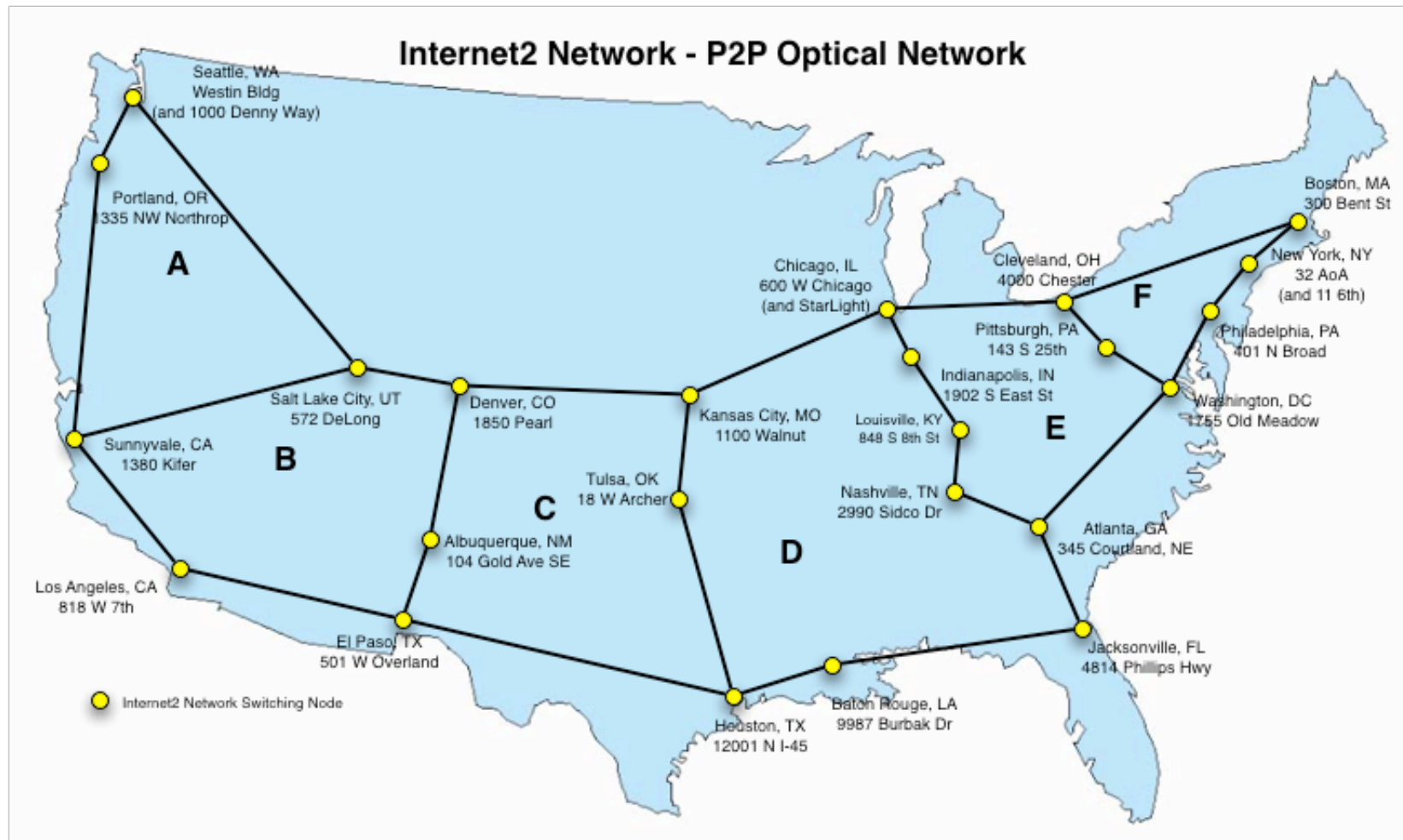
DWDM Topology



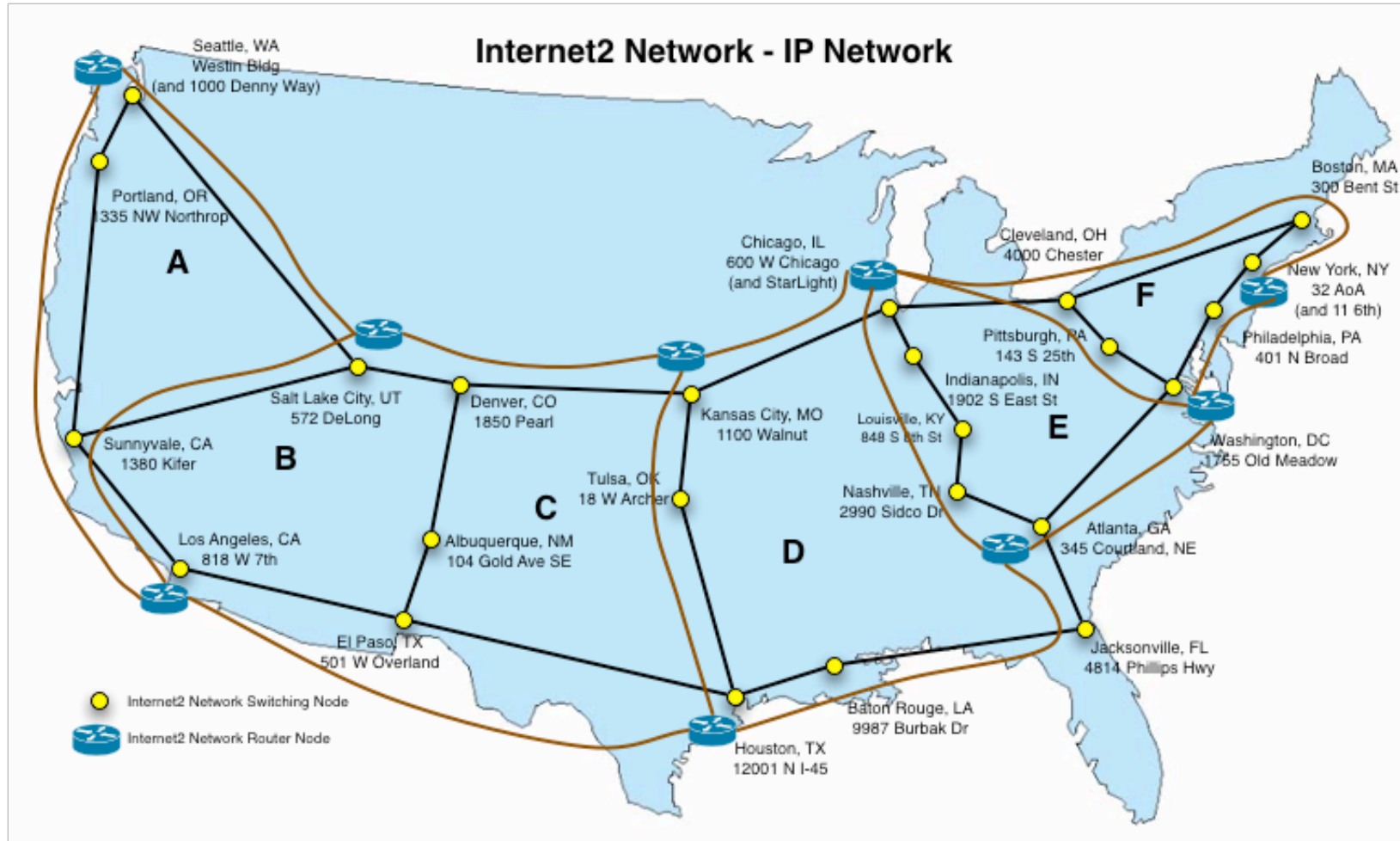
DWDM Topology



P2P Optical Topology

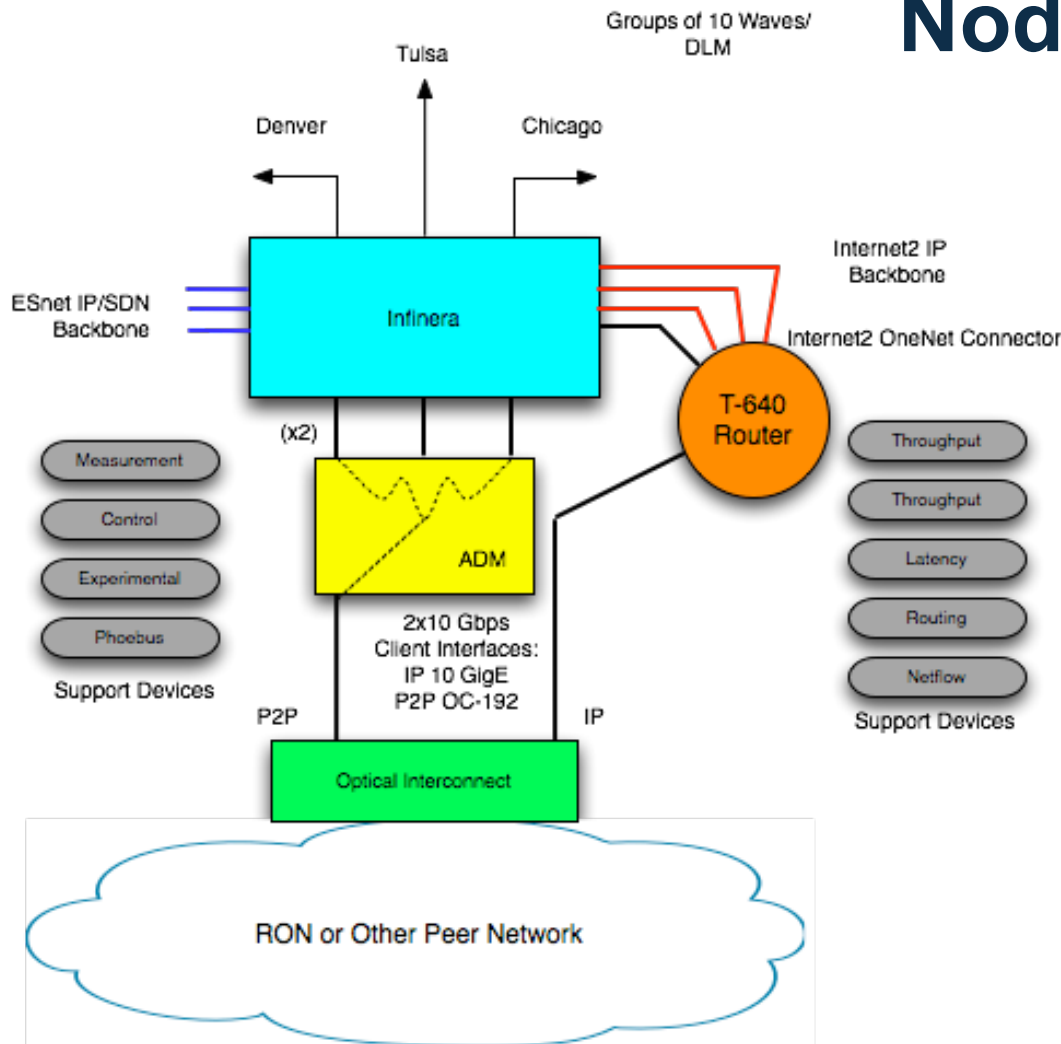


IP Network



Kansas City, MO

Connector: GPN



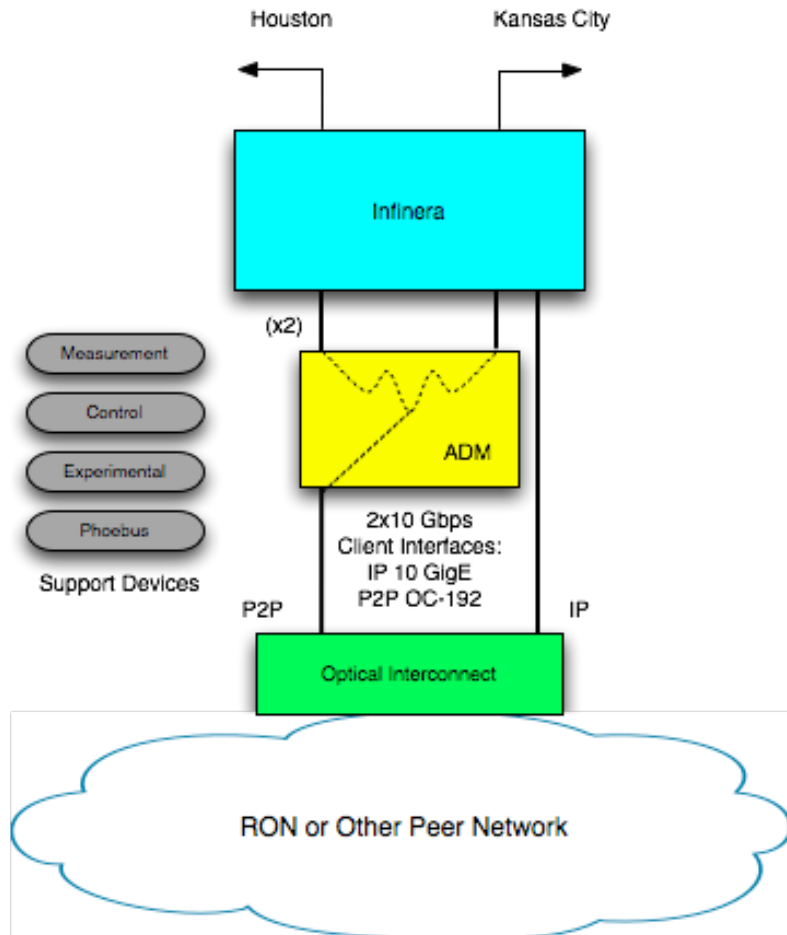
Node Architecture

- Infinera DWDMGear - Static at the start
- Grooming capabilities in ADM to provide sub channels and HOPI types of activities at the start
- Simplified and standardized interface to connectors, exchange points, and other global research and education networks - 2 x 10 Gbps interfaces
- Measurement and control servers will support the node

Tulsa, OK

Connector: OneNet

Groups of 10 Waves/
DLM



Node Architecture

- Example of Optical only Node for connected RON or Peer Network

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Timeline

- Build-Out:
 - November 15, 2006: NYC - PHL - DC - PIT - CLEV - CHIT
 - March 15, 2007: West to Denver
 - June 15, 2007: West to LA and Seattle
- Transition
 - From Abilene to new Internet2 Network by October 2007
- Control Plane deployment evolves over this time period
 - Would like to be able to implement ASTs across domains by October of 2007
- HOPI Testbed will be transitioned to the new network over the next 2 months

Control Plane

- Nodes
 - Infinera DWDM Equipment - GMPLS control plane
 - Will be static at the beginning
 - Grooming Equipment (e.g. Nortel OME6500 or Ciena Core Director)
 - Will provide dynamic services at the start
 - Using DRAGON high level services
 - At router nodes, Juniper Routers - GMPLS implementation
- Integration of control planes
- Partnership between Infinera, Juniper, and Internet2

DWDM Equipment

- Infinera GMPLS testing and setup
 - Configuration of waves across system by hand
 - Interfacing with other networks
 - Interfacing between T-640s and Infinera gear using UNI
 - Will remain static at the start, to be added to the dynamic services as integration proceeds

Grooming Equipment

- Final decision on vendor soon
 - Details of dynamic service will depend on the equipment chosen
- Connection to several waves at the start
- SONET on the backbone
- Must support GFP, VCAT, and LCAS
- Integration of DRAGON software will depend on equipment. Two possible directions:
 - Strong dependence on DRAGON software
 - Strong dependence on vendor software

Control Plane

- Control Plane Activities - DRAGON software. How will these be integrated? Still an open question.
 - CSA - Client System Agent - Uni for applications
 - VLSR - Virtual Label Switched Router
 - NARB - Network Access Resource Broker
 - ASTs - Application Specific Topologies. Successful demonstrations of these at Internet2 member meeting
- Specific types of services
 - Immediate reservation - who will use this? Bandwidths?
 - Advanced reservation - will network utilization be good?
- Need to incorporate - would be good if we could share code
 - AAA
 - Security
 - Scheduling

Contact Information

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