GLIF Control Plane meeting

Chair: Gigi Karmous-Edwards and Secretary: Licia Florio

September 11th and 12th, 2006

Tokyo

glif

Sept 11th and 12th Control Plane Agenda

- Monday, 11 September 2006 (16:00-18:00)
 - * Opening and Welcome Gigi Karmous-Edwards, MCNC
 - * GEANT2/JRA3 efforts in the Control Plane Area Victor Reijs, HEAnet
 - * Ethernet over the WAN John Graham, ULCC
 - * G-Lambda and Enlightened Middleware and Control Plane interactions -Tomohiro Kudoh, AIST
- Tuesday, 12 September 2006 (08:30-13:00)
 - * Liaison with GGF GGHP working group Gigi Karmous-Edwards, MCNC
 - * InterDomain Peering and Provisioning via Web Services and (G)MPLS Tom Lehman, USC-ISI
 - * Control Plane Strategy NLR (speaker TBC)
 - * Control plane Strategy Rick Summerhill, Internet2
 - * Inter-domain progress between US and Japan Tomohiro Otani, NICT
 - * Discussion about future actions
 - * Conclusion



Why is the Control Plane important to GLIF?

Today

- End-to-end Optical connections between two laboratories across the Globe:
- takes "lots of phone calls"
- takes "lots of emails"
- tens of people
- connection becomes relatively static
- over three weeks!!!!
- Failed link may result in days of out-of service

We want to...

- applications/sensors/endusers/instruments to initiate an end-to-end connection
- Resources for short periods of time or long depending on application
- We want automatic recovery restoration/protection

•How do we as a community go from where we are today to what we really want?

•We need to use the Morphnet concept in the GLIF community....

•(Part of the infrastructure for vertical integration research and other part as production)



GLIF Automation?



September 11th and 12th

Control Plane Challenges For GLIF Migrating towards Automation....

Taking one baby step at a time ...

- CIM Common Information Base translation of repository to machine based
- Common Services repository
- WEB services based services towards automation
- Translation of administrative policy to low-level policy for automation
- Scheduling services
- Automated Testing and monitoring
- Control plane protocols (GMPLS, SIP)
- Policy and Security
- Interdomain routing



GLIF Control Plane and Grid Middleware Integration

<u>Mission</u>: To agree on the interfaces and protocols to automate and use the control planes of the contributed Lambda resources to help users on a global scale access optical resources on-demand or pre scheduled.

several key areas we need to focus on:

- Define and understand real operational scenarios
- Defining a set of basic/common services:
 - Precise definitions
 - Developing semantics the whole community agrees to for machine to machine communications
- Interdomain exchange of information for both control planes and management planes
 - Determine what information needs to be monitored
 - How to abstract monitored information to share
- Determine what existing standards are useful vs. where Grid requirements are unique and new services and concepts are required
 - How do we standardize mechanisms and protocols that are unique to the Grid community
- Define a Grid control plane architecture
- Work closely with E-science applications to provide vertical integration





One Definition of Control Plane

"Infrastructure and distributed intelligence that controls the establishment and maintenance of connections in the network, including protocols and mechanisms to disseminate this information; and algorithms for engineering an optimal path between end points." Draft-ggf-ghpn-opticalnets-1



Control Plane Functions

- <u>Routing</u> Intra-domain and Inter-domain
 - 1) automatic topology and resource discovery
 - 2) path computation (How do we use the infrastructure)
- <u>Signaling</u> standard communications protocols between network elements for the establishment and maintenance of connections
- <u>Neighbor discovery</u> NE sharing of details of connectivity to all its neighbors (very powerful tool)
- <u>Local resource management</u> accounting of local available resources



Control Plane



"Planes"

- Global
- Distributed and resilient
- Non-manual, i.e., automated
- Separated from the data plane

Network-wide, global, comprehensive, distributed, automated software system that enables interoperability, responsiveness, flexibility, enhanced access to network resources, and, speed and efficiency gain

Previous Talks and Discussions

- iGrid 2005 San Diego, Ca 9/30/05
 - First Control Plane meeting
- Joint session w/ Tech group
 - Explored means of collecting and administrating GLIF repository
 - Repository three talks
 - DNS approach
 - database and maps
 - RDF meta-data approach
- Control Plane working group session
 - Defining Common Service definitions
 - Monitoring and testing for verification of services.
 - We also explored SOA as a means for automation



Previous Talks and Discussions

Common Service Definitions

- Common Service Definition that describes what a service should deliver detailed parameters, ie.
- The same model should be used by users to indicate what they have received verify service
- UCLP and SOA
 - UCLP web services allows end users to self provision and dynamically reconfigure optical networks
 - Service Oriented Architecture, (SOA) :
 - Utilizing a concept known as Google Mash-ups
- Testing and Monitoring
 - For end-2-end connections
 - Some requirements for verification
 - Automation



What have we done?This first year

- What did we do right? And how can we do it better?
- What have we accomplished?
 - Open forum to discuss control plane issues and plans for moving forward
 - List discussions
 - Sharing of ideas and sometimes software and specifications
- What should we do in the near future?
 - More GLIF documents written by the community?
 - WIKI
- Collaboration with the GHPN group
 - We will work towards a common document for both groups on
 - Service Definitions
- Moving Forward...

- Links to open source software to be shared with the community GLIF 2006, Tokyo

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